Dragone Telescope Trade-off Study

Young + Hanany

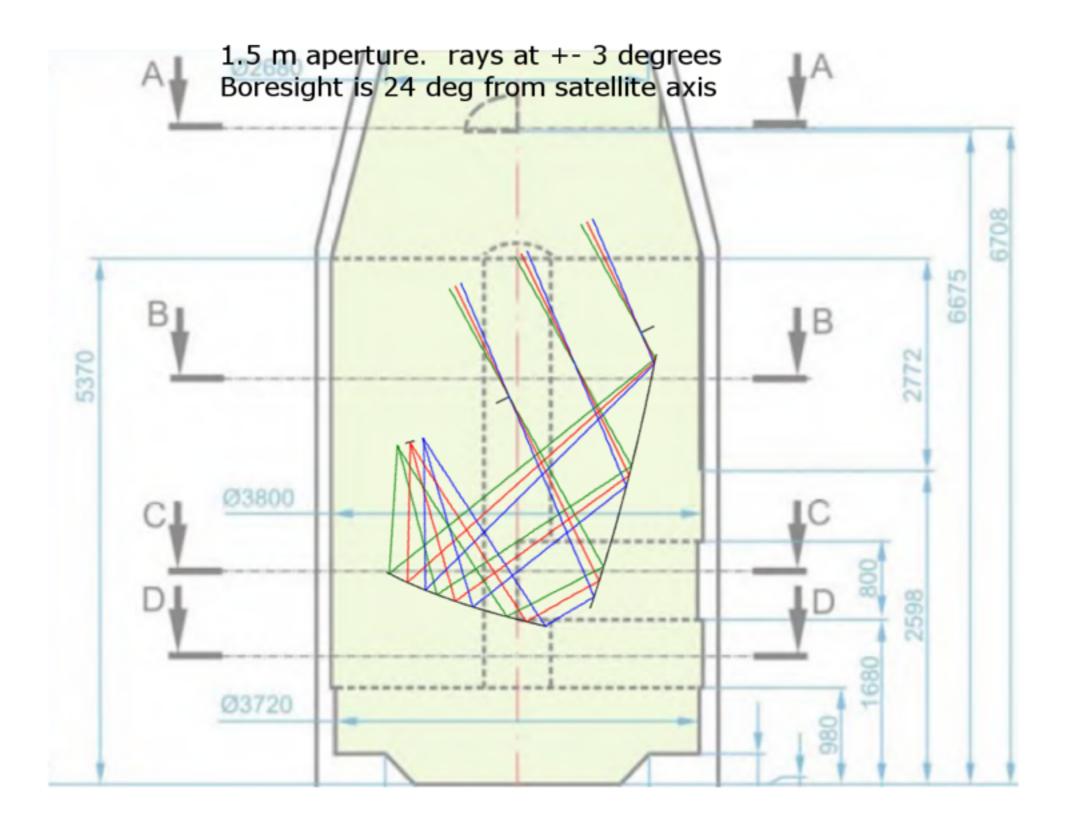
Actions from Last Week

- Provide 1.5 m open dragone design to Neil
 - Status: complete
- Investigate folding the focal plane
 - Status: not doable with current 1.5 m aperture design
- 1 m vs. 1.5 m in terms of # of feeds
 - Status: no gain; see slide 3 (note: for non-optimized systems)
- Set off-axis angle to 24 degrees
 - status: slide 4
 - Can provide solid model
 - Need to check extent of primary in/out of page.
- Provide FOV as a function of frequency
 - Status: Slide 5 (for core light, non-optimized)
 - Need to check whether satisfies requirements
 - Need to provide for core extended
- Other trade-offs?
 - 1 m vs. 1.5 optimized: is there net gain in # of pixels?
 - 1 m vs. 1.5 m optimized: is the gain in volume (for folding the optics) worth the reduction in resolution?

of pixels vs aperture size

- Assumption: pix. linear size scales linearly with f#
- # of pixels = [linear FOV](rad)*platescale (cm/rad) / [pix. linear size] (cm)
- plate scale = f# * [aperture diameter](cm)
- # of pixels = [linear FOV](rad)*f#*[aperture diameter] (cm/rad) / [pix. linear size] (cm)
- empirical: [linear FOV] scales inversely with [aperture diameter]
 - (for non optimized systems)
- [pix. linear size] scales linearly with f#, so for fixed f#, [f#/pix.linear size] is fixed.
- Conclusion: for fixed f#, # of pixels are fixed

Boresight Angle at 24 deg.



Available FOV vs. Frequency

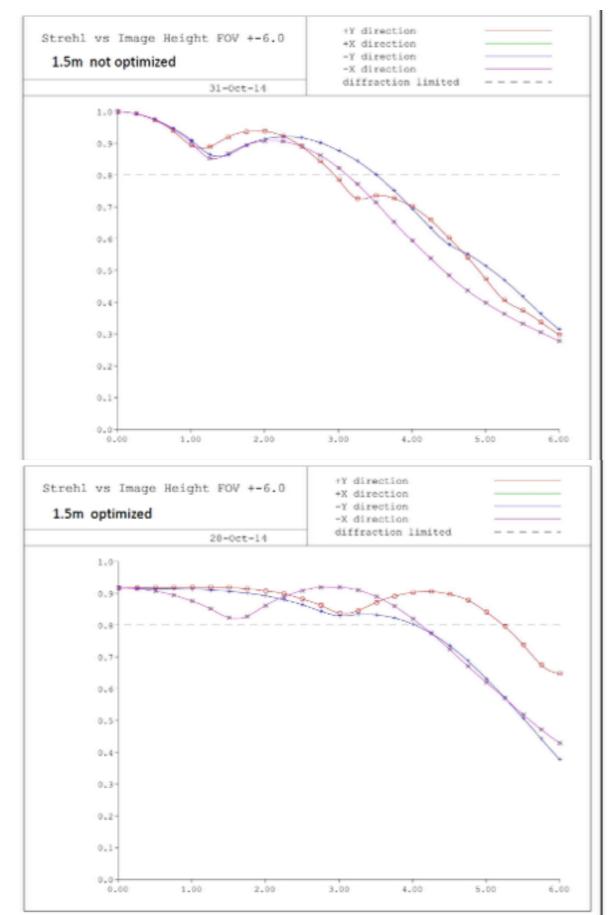
| Frequency | N_detectors (2 x N_horns) | Lambda | Beam size | Linear FOV, Az | Linear FOV, El | Focal Plane Diameter | |
|-----------|---------------------------------|------------|-----------|-------------------|-------------------|----------------------|------|
| | | | | | | Az | El |
| (GHz) | | (mm) | (arcmin) | (deg) | (deg) | (cm) | (cm) |
| 60 | 10 | 5 | 21.0 | 10.8 | 12 | 47 | 52 |
| 90 | 30 | 3.33333333 | 14.0 | 8.8 | 9.4 | 38 | 41.5 |
| 130 | 160 | 2.30769230 | 9.7 | 7 | 7.2 | 30 | 31.5 |
| 160 | 260 | 1.875 | 7.9 | 5.8 | 6.1 | 26 | 27 |
| 220 | 200 | 1.36363636 | 5.7 | 4.4 | 4.6 | 20 | 20.2 |
| 340 | 40 | 0.88235294 | 3.7 | 3 | 3 | 13 | 13.3 |
| 450 | 20 | 0.66666666 | 2.8 | 2.4 | 2.3 | 10.2 | 10.2 |
| 600 | 20 | 0.5 | 2.1 | 1.8 | 1.75 | 7.8 | 7.7 |

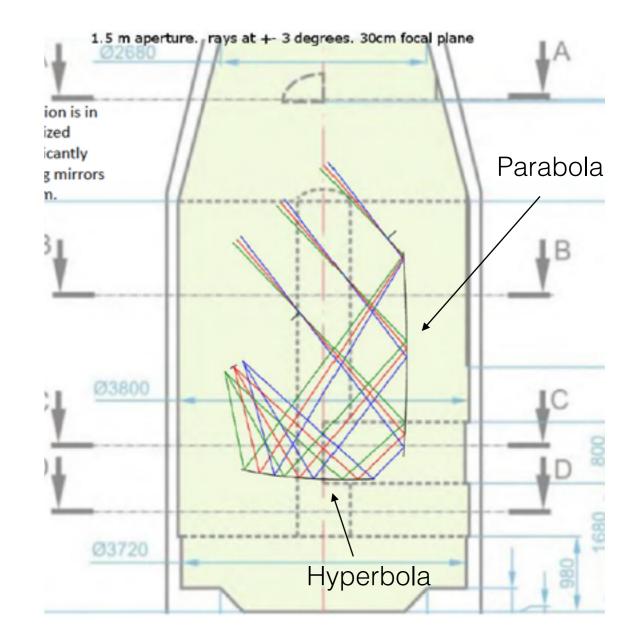
Common Threads

- Compare crossed, front-fed, and Gregorian Dragone designs
- All f#~2
- No reimaging optics
- Use plain conics, and optimize with higher order aspherics at 150 GHz (more details in additional slides)
- Fit 1.5 m aperture in shroud

Slides from Last Week

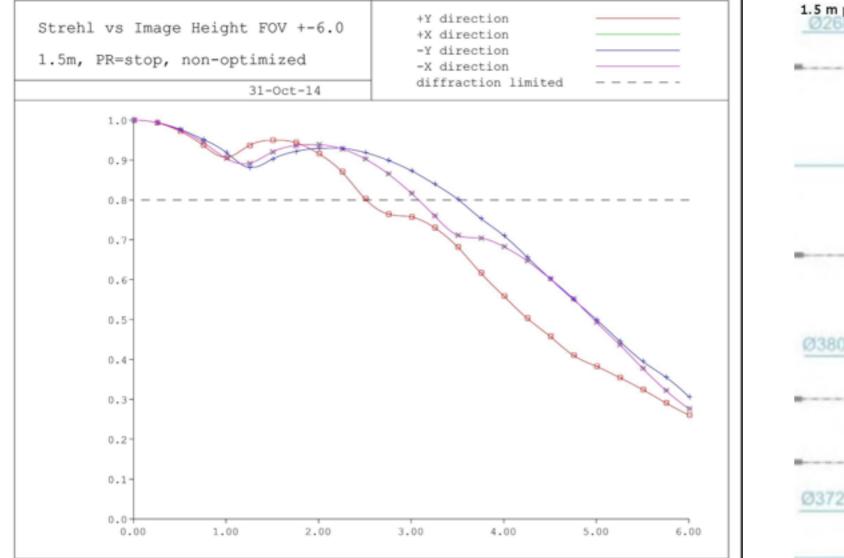
Front Fed Dragone - I - Front Stop

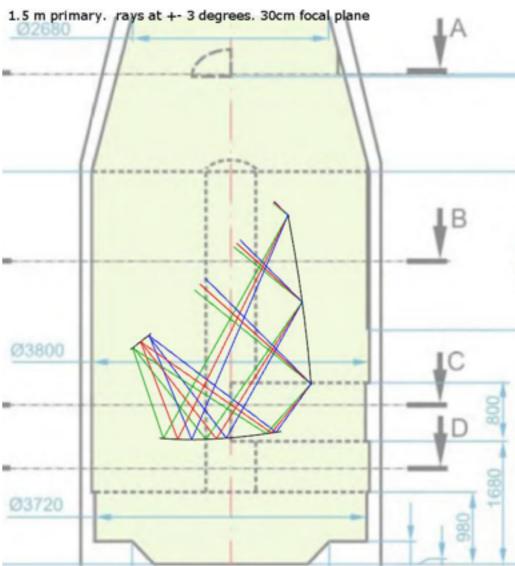




- f#=~2
- 6 deg FOV above Strehl 0.8 (@ 150 GHz) not optimized
- 8 deg FOV optimized
- plate scale = 4.4 cm/deg

Front Fed Dragone - II - Primary Stop

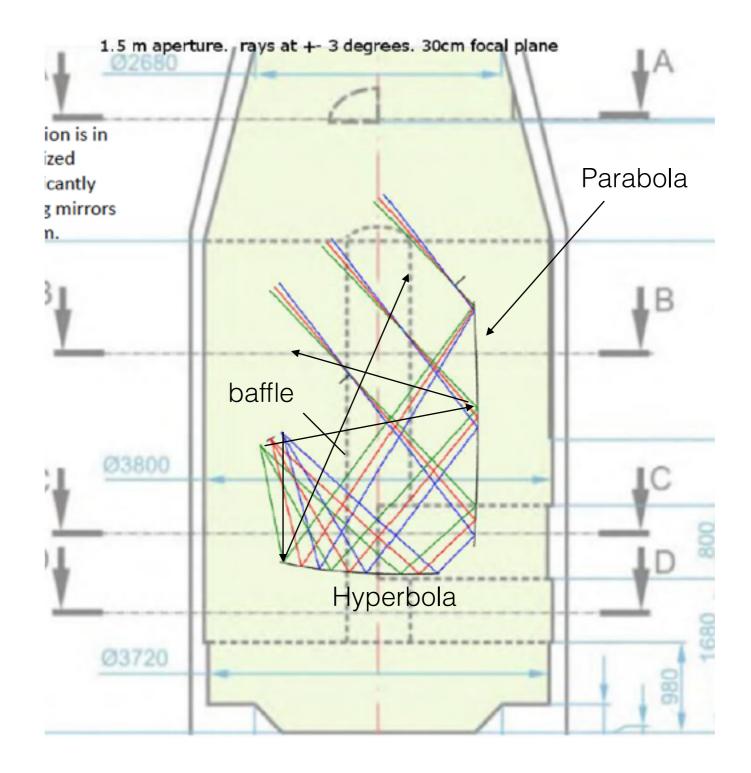




- Not Optimized
- f#=~2
- Conclusion 1: For non-optimized telescopes FOV largely independent of stop location
- Plate scale = 4.2 cm/deg

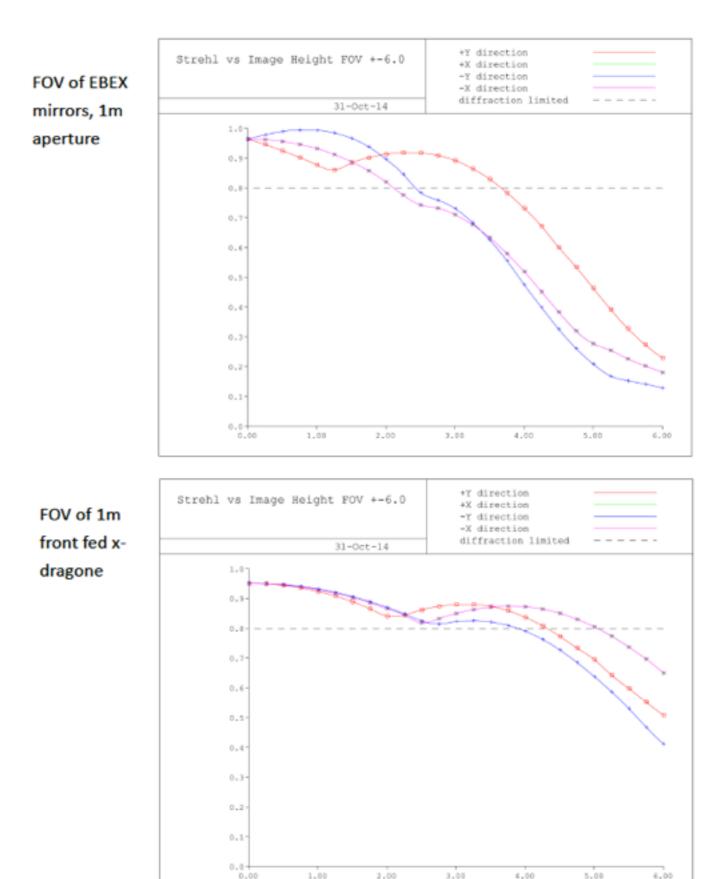
Front Fed Dragone - Sidelobs

• At first look sidelobes appear to be manageable.

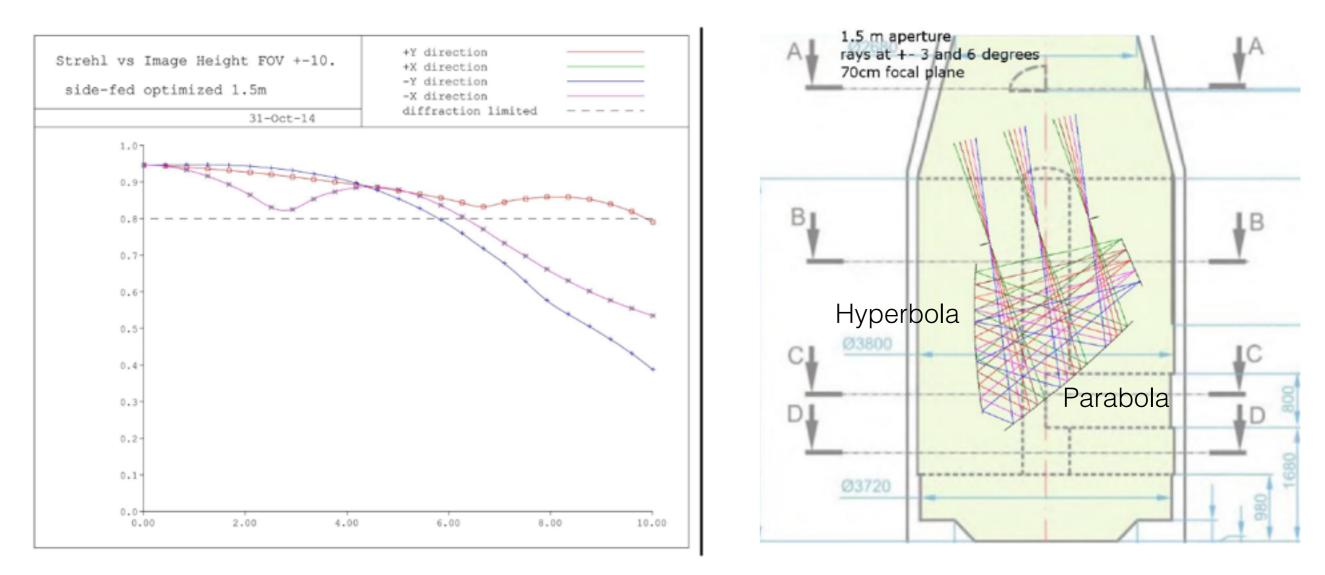


Gregorian vs. Front-Fed Dragone

- Same aperture (1 m)
- Both not optimized
- Plate scale = 3.2-3.3 cm/deg
- EBEX (Gregorian, telescope only): 5 deg FOV
- Front Fed: ~8 deg FOV
- Conclusion 2: comparing 1 m to 1.5 m (not optimized) looks like throughput is conserved. There is gain in FOV at expense of beam size.

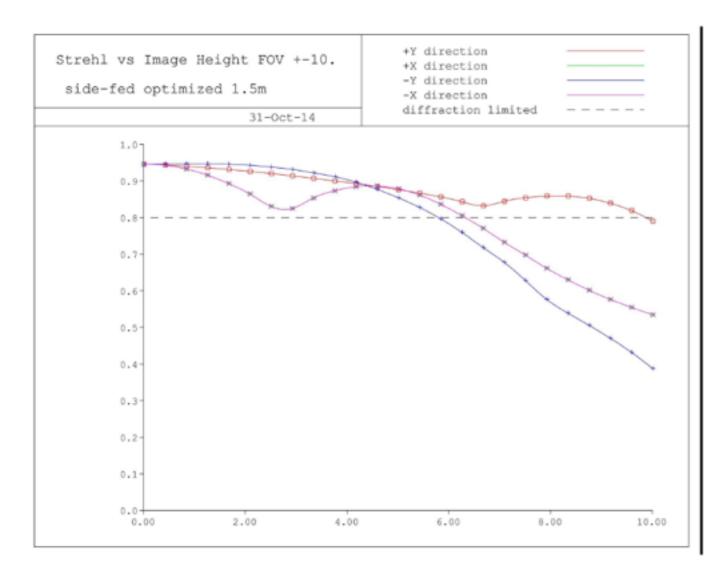


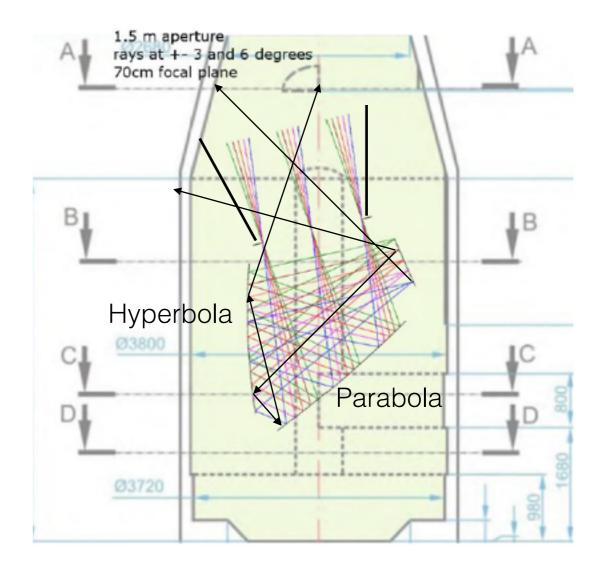
Crossed Dragone - Front Stop



- Optimized
- f#=2.7
- 6 deg FOV
- But note differences in f#. If normalize back to f#=2, [(2/2.7)*6]=4.4 deg FOV
- Conclusion 3: DLFOV increases somewhat faster than f#.

Crossed Dragone - Stray Light





- Issues
 - Three bounces
 - Direct view of sky
- Would further increasing f# solve the issue?

Cold Aperture Stop for COrE+

- Why aperture stop? To control sidelobes by controlling the illumination on the primary mirror.
- Why cold? To reduce loading on the detectors
- Does COrE+ need a stop?
 - Depends on how beams are coupled to free space
 - Planck does not have a stop. WMAP did not have a stop. Beams are coupled with feedhorns. Sidelobes are measured sufficiently well for mission goals.
 - For COrE+ Sidelobes will need to be measured as well, modeled and accounted for.
 - Are asymmetrical beams an issue? To first order no, if the asymmetry is the same for both polarization states then no beam leakage of T to P.

Now Studying

- Fix f# at 2
- Optimize the 1 meter version
 - front fed: check for FOV
 - crossed Dragone: check for stray light
- Check stray light with side-fed Dragone
- Performance vs. Frequency

Additional Slides

Optimization

- optimize WFE over FOV
 - uniform distribution of fields
- adding aspherics, adjusting defocus and mirror curvatures, and allowing one of the Dragone angles to vary